

# 1 Minimal Realizations

**Definition:** A realization  $(A, B, C)$  is *minimal* if  $(A, B)$  is controllable and  $(A, C)$  is observable.

**Theorem:** For any  $(A, B, C)$  there exists a nonsingular similarity transformation  $T$  that transforms the original system into the form

$$\bar{A} = T^{-1}AT = \begin{bmatrix} A_{co} & 0 & A_o & 0 \\ A_c & A_{c\bar{o}} & A_1 & A_2 \\ 0 & 0 & A_{\bar{c}o} & 0 \\ 0 & 0 & A_3 & A_{\bar{c}\bar{o}} \end{bmatrix}, \quad \bar{B} = T^{-1}B = \begin{bmatrix} B_{co} \\ B_{c\bar{o}} \\ 0 \\ 0 \end{bmatrix},$$

$$\bar{C} = CT = [C_{co} \ 0 \ C_{\bar{c}o} \ 0].$$

In this form:

1) The subsystem  $(A_{co}, B_{co}, C_{co})$  is controllable and observable and  $C(sI - A)^{-1}B = C_{co}(sI - A_{co})^{-1}B_{co}$ ;

2) The subsystem

$$\left( \begin{bmatrix} A_{co} & 0 \\ A_c & A_{c\bar{o}} \end{bmatrix}, \begin{bmatrix} B_{co} \\ B_{c\bar{o}} \end{bmatrix}, [C_{co} \ 0] \right)$$

is controllable;

3) The subsystem

$$\left( \begin{bmatrix} A_{co} & A_o \\ 0 & A_{\bar{c}o} \end{bmatrix}, \begin{bmatrix} B_{co} \\ 0 \end{bmatrix}, [C_{co} \ C_{\bar{c}o}] \right)$$

is observable;

4) The subsystem  $(A_{\bar{c}\bar{o}}, 0, 0)$  is neither controllable nor observable.

**Problem:** Given a non-minimal realization  $(A, B, C, D)$  find an equivalent realization  $(\bar{A}, \bar{B}, \bar{C}, \bar{D})$  that is minimal.

## 2 The Singular Value Decomposition

**Theorem:** For any matrix  $A \in \mathbb{R}^{m \times n}$  with  $\text{rank}(A) = r < n$  there exist real square matrices

$$U = [U_1 \ U_2], \quad V = [V_1 \ V_2],$$

and a diagonal real matrix

$$\Sigma = \begin{bmatrix} \Sigma_+ & 0 \\ 0 & 0 \end{bmatrix},$$

such that

$$A = U\Sigma V^T = [U_1 \ U_2] \begin{bmatrix} \Sigma_+ & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} V_1^T \\ V_2^T \end{bmatrix},$$

where

$$UU^T = U_1U_1^T + U_2U_2^T = I, \quad VV^T = V_1V_1^T + V_2V_2^T = I,$$

and  $\Sigma_+ > 0$ .

**Proof:** There exists orthogonal  $U$  and  $V$  such that

$$AA^T = U\Lambda_1U^T, \quad A^TA = V\Lambda_2V^T,$$

where  $\Lambda_1 \geq 0$ ,  $\Lambda_2 \geq 0$ . Also, if  $A = U\Sigma V$  then

$$\begin{aligned} AA^T &= U\Sigma V^T V \Sigma^T U^T = U\Sigma\Sigma^T U^T, \\ A^TA &= V\Sigma^T U^T U \Sigma V^T = V\Sigma^T \Sigma V^T. \end{aligned}$$

One can prove that the choice

$$\Lambda_1 = \Sigma\Sigma^T, \quad \Lambda_2 = \Sigma^T\Sigma,$$

is possible.

### 3 Computing Minimal Realizations

#### 3.1 Computing Controllable Realizations

Let  $(A, B, C)$  be a non-minimal realization.

- 1) Compute  $\mathcal{C}(A, B)$ .
- 2) Compute the singular value decomposition

$$\mathcal{C}(A, B) = [U_1 \ U_2] \begin{bmatrix} \Sigma_+ & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} V_1^T \\ V_2^T \end{bmatrix} = U_1 \Sigma_+ V_1^T,$$

where  $\Sigma_+ > 0$  and

$$U_1 U_1^T + U_2 U_2^T = I, \quad V_1 V_1^T + V_2 V_2^T = I.$$

- 3) Set

$$r = \text{rank } \mathcal{C}(A, B) = \dim \Sigma_+.$$

- 4) Compute

$$R_1 = U_1 \Sigma_+^{-1/2} \quad T_1 = U_1 \Sigma_+^{1/2}.$$

**Theorem:** The realization

$$(\bar{A}, \bar{B}, \bar{C}) = (R_1^T A T_1, R_1^T B, C T_1)$$

of order  $r$  is controllable and  $B(sI - A)^{-1}C = \bar{B}(sI - \bar{A})^{-1}\bar{C}$ .

**Proof:** First note that

$$U^T U = \begin{bmatrix} U_1^T \\ U_2^T \end{bmatrix} [U_1 \ U_2] = \begin{bmatrix} I & 0 \\ 0 & I \end{bmatrix}, \quad \Rightarrow \quad U_1^T U_1 = I,$$

so that for

$$P = P^T = R_1 T_1^T = U_1 \Sigma_+^{-1/2} \Sigma_+^{1/2} U_1^T = U_1 U_1^T$$

we have

$$PC(A, B) = (U_1 U_1^T)(U_1 \Sigma_+ V_1^T) = U_1 \Sigma_+ V_1^T = \mathcal{C}(A, B).$$

That is

$$PC(A, B) = \begin{bmatrix} PB & PAB & \cdots & PA^{n-1}B \end{bmatrix} = \begin{bmatrix} B & AB & \cdots & A^{n-1}B \end{bmatrix}.$$

Therefore

$$\begin{aligned} (AP)B &= A(PB) = AB, \\ (AP)^2B &= AP(APB) = AP(AB) = A(PAB) = A^2B, \\ &\vdots \\ (AP)^nB &= APA^{n-1}B = A^nB. \end{aligned}$$

Consequently

$$\begin{aligned} \bar{A}^i \bar{B} &= (R_1^T AT_1)^i R_1^T B, \\ &= (R_1^T AT_1)(R_1^T AT_1) \cdots (R_1^T AT_1) R_1^T B, \\ &= R_1^T (AT_1 R_1^T)(AT_1 R_1^T) \cdots (AT_1 R_1^T) B, \\ &= R_1^T (AP)^i B, \\ &= R_1^T A^i B, \end{aligned}$$

so that

$$\begin{aligned} \mathcal{C}(\bar{A}, \bar{B}) &= \begin{bmatrix} \bar{B} & \bar{A}\bar{B} & \cdots & \bar{A}^{n-1}\bar{B} \end{bmatrix}, \\ &= R_1^T \begin{bmatrix} B & AB & \cdots & A^{n-1}B \end{bmatrix}, \\ &= R_1^T \mathcal{C}(A, B) \end{aligned}$$

As  $R_1$  has full-column,  $\text{rank } \mathcal{C}(\bar{A}, \bar{B}) = r$  and therefore  $(\bar{A}, \bar{B})$  is controllable. Finally remember that

$$C(sI - A)^{-1}B = \sum_{i=1}^{\infty} H_i, \quad H_i = CA^{i-1}B.$$

Since

$$\begin{aligned} \bar{H}_i &= \bar{C}(\bar{A}^{i-1}\bar{B}), \\ &= (CT_1)(R_1^T A^{i-1}B), \\ &= C(PA^{i-1}B), \\ &= C(A^{i-1}B) = H_i, \end{aligned}$$

we conclude that

$$C(sI - A)^{-1}B = \bar{C}(sI - \bar{A})^{-1}\bar{B}.$$

### 3.2 Computing Observable Realizations

Let  $(A, B, C)$  be a non-minimal realization.

1) Compute  $\mathcal{O}(A, C)$ .

2) Compute the singular value decomposition

$$\mathcal{O}(A, C) = \begin{bmatrix} U_1 & U_2 \end{bmatrix} \begin{bmatrix} \Sigma_+ & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} V_1^T \\ V_2^T \end{bmatrix} = U_1 \Sigma_+ V_1^T,$$

where  $\Sigma_+ > 0$  and

$$U_1 U_1^T + U_2 U_2^T = I, \quad V_1 V_1^T + V_2 V_2^T = I.$$

3) Set

$$r = \text{rank } \mathcal{O}(A, C) = \dim \Sigma_+.$$

4) Compute

$$R_1 = V_1 \Sigma_+^{1/2} \quad T_1 = V_1 \Sigma_+^{-1/2}.$$

**Theorem:** The realization

$$(\bar{A}, \bar{B}, \bar{C}) = (R_1^T A T_1, R_1^T B, C T_1)$$

of order  $r$  is observable and  $B(sI - A)^{-1}C = \bar{B}(sI - \bar{A})^{-1}\bar{C}$ .

**Proof:** Note that

$$P = P^T = R_1 T_1^T = V_1 \Sigma_+^{1/2} \Sigma_+^{-1/2} V_1^T = V_1 V_1^T$$

and

$$P \mathcal{O}(A, C)^T = (V_1 V_1^T)(U_1 \Sigma_+ V_1^T)^T = \mathcal{O}(A, C)^T$$

and follow the same steps as in the previous proof.

### 3.3 Computing Minimal Realizations

Let  $(A, B, C)$  be a non-minimal realization.

- 1) Compute  $\mathcal{C}(A, B)$  and  $\mathcal{O}(A, C)$ .
- 2) Compute the singular value decomposition

$$\mathcal{C}(A, B) = \begin{bmatrix} U_c & U_{\bar{c}} \end{bmatrix} \begin{bmatrix} \Sigma_c & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} V_c^T \\ V_{\bar{c}}^T \end{bmatrix} = U_c \Sigma_c V_c^T,$$

where  $\Sigma_c > 0$  and

$$U_c U_c^T + U_{\bar{c}} U_{\bar{c}}^T = I, \quad V_c V_c^T + V_{\bar{c}} V_{\bar{c}}^T = I.$$

- 3) Compute the singular value decomposition

$$\mathcal{O}(A, C) U_c \Sigma_c^{1/2} = \begin{bmatrix} U_{co} & U_{\bar{co}} \end{bmatrix} \begin{bmatrix} \Sigma_{co} & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} V_{co}^T \\ V_{\bar{co}}^T \end{bmatrix} = U_{co} \Sigma_{co} V_{co}^T,$$

where  $\Sigma_{co} > 0$  and

$$U_{co} U_{co}^T + U_{\bar{co}} U_{\bar{co}}^T = I, \quad V_{co} V_{co}^T + V_{\bar{co}} V_{\bar{co}}^T = I.$$

- 4) Set

$$r = \text{rank } \mathcal{O}(A, C) T_c = \dim \Sigma_{co}.$$

- 5) Compute

$$R_1 = U_c \Sigma_c^{-1/2} V_{co} \Sigma_{co}^{1/2} \quad T_1 = U_c \Sigma_c^{1/2} V_{co} \Sigma_{co}^{-1/2}.$$

**Theorem:** The realization

$$(\bar{A}, \bar{B}, \bar{C}) = (R_1^T A T_1, R_1^T B, C T_1)$$

of order  $r$  is a minimal realization.

**Proof:** Combine the two previous theorems.